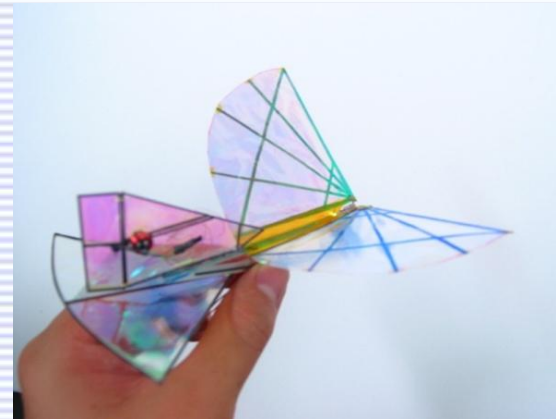
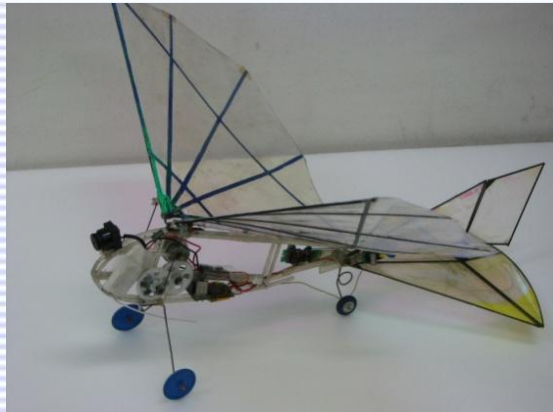
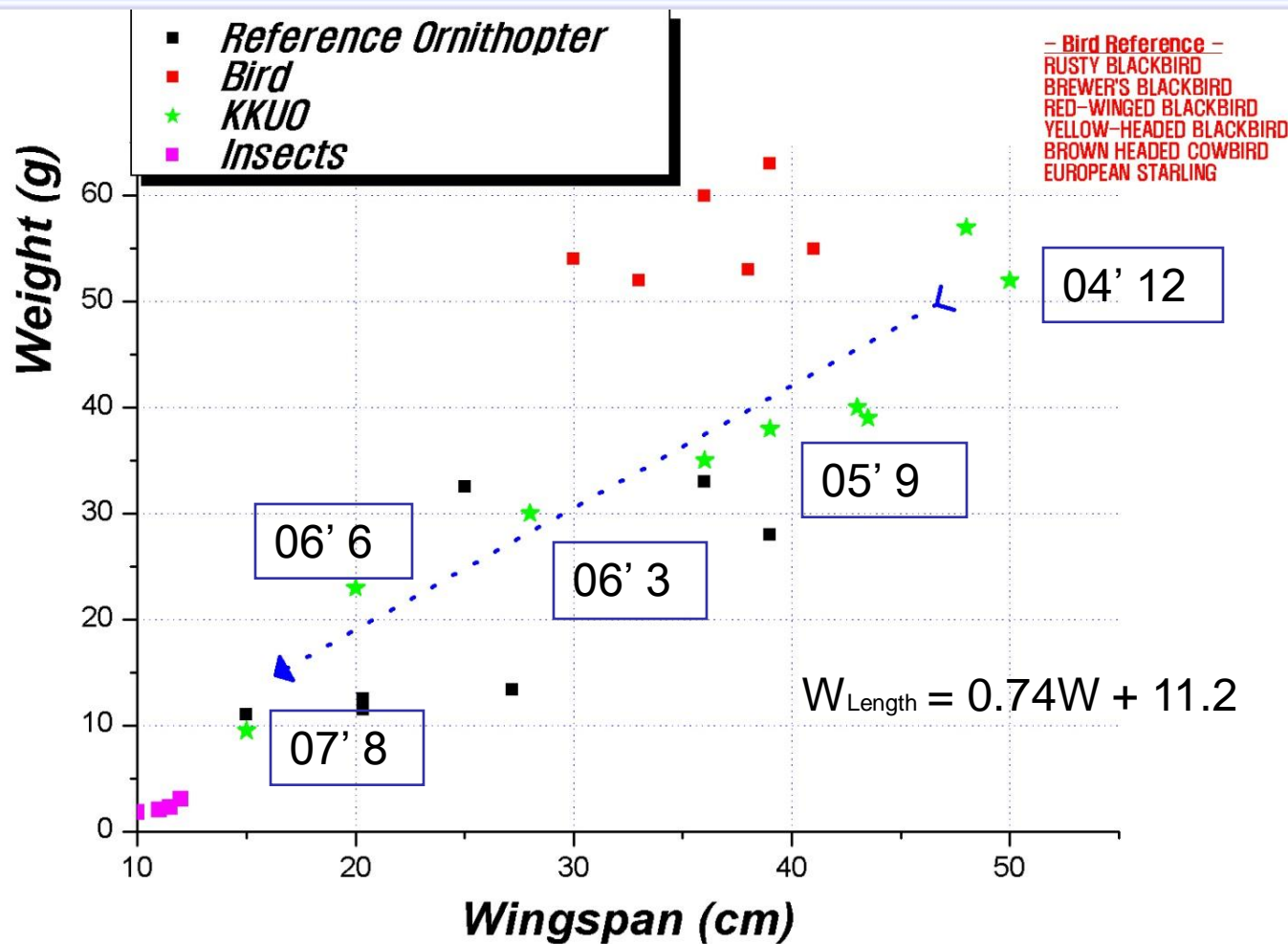


Flapping MAV



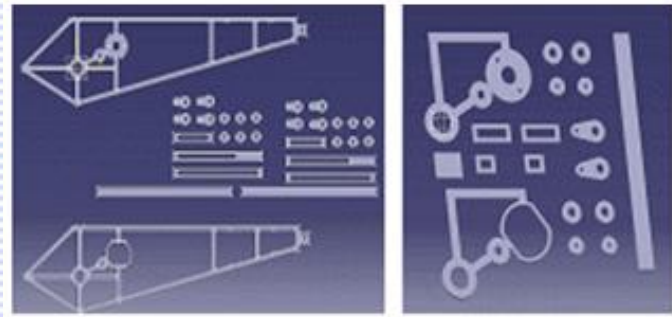
**Park Joon Hyuk, Kim Hyung Jin,
Kwang Joon Yoon**
Smart Robot Center
Dept. of Aerospace Information Eng.
Konkuk University
Seoul, Korea

- **Characteristics**
 - Materials
 - Research on wing structure motivated by insect wing
- **36cm Flapping MAV**
 - capable of vision sensing and Take-off/Landing
- **28cm Flapping MAV**
- **15cm Flapping MAV**



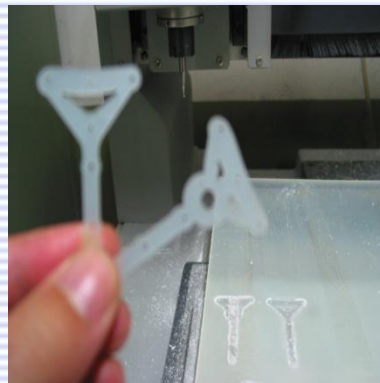
Characteristics – materials

- Designed using CATIA



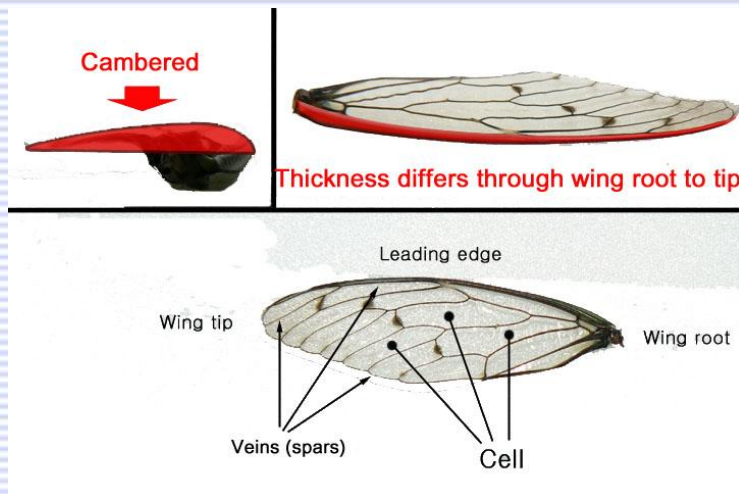
- Materials
 - Body : glass/epoxy
 - Wing frame & shaft : carbon rod
 - Wing skin : epoxy film

- Manufacture by CNC machine

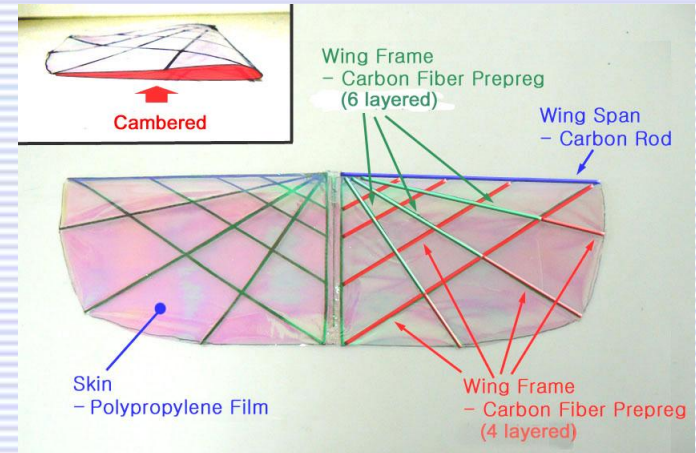


Characteristics – wings

- **Wing Shape Configuration**
- Insect wing(cicada) analysis

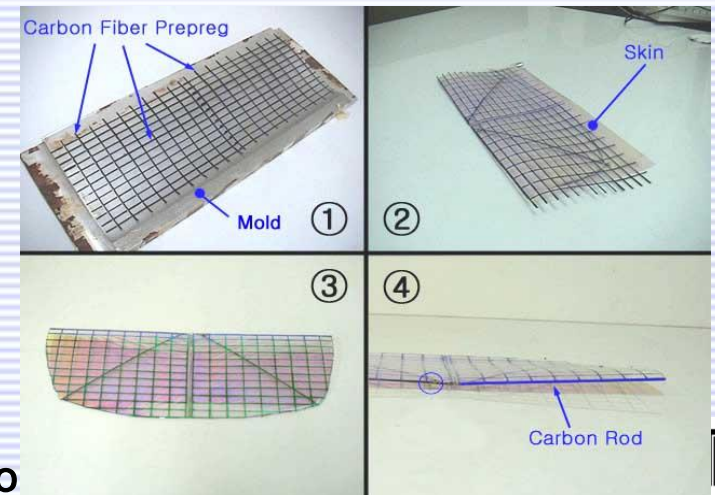


- Bio-mimetic wing design



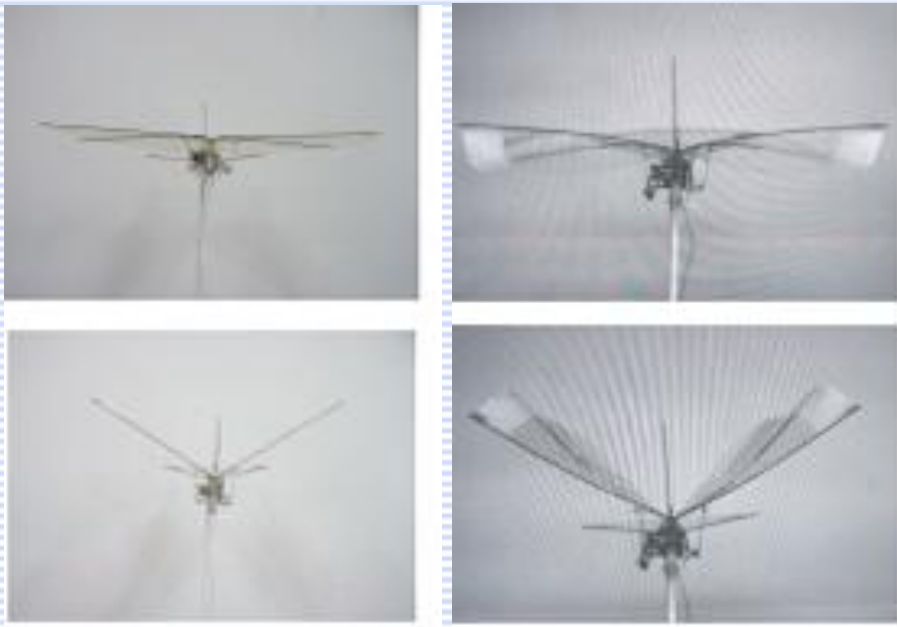
- Characteristics of insect wing
 - Cell-type wing
 - Camber wing on both spanwise and chord direction

- Procedures



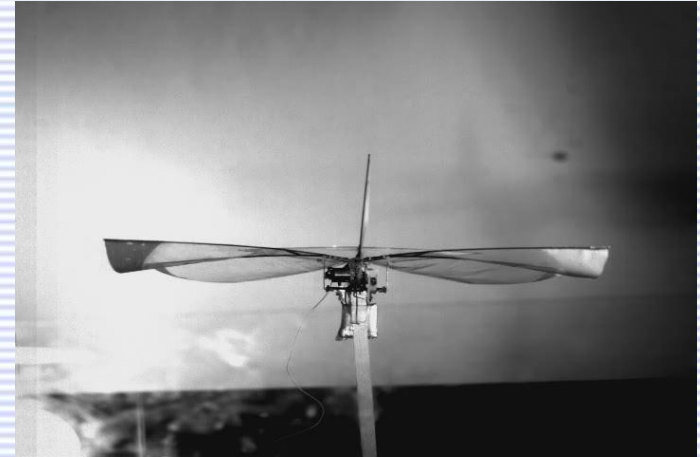
Characteristics – wings

- **Wing Shape Configuration**
- The deformed shape of ornithopter wings during the flapping motion

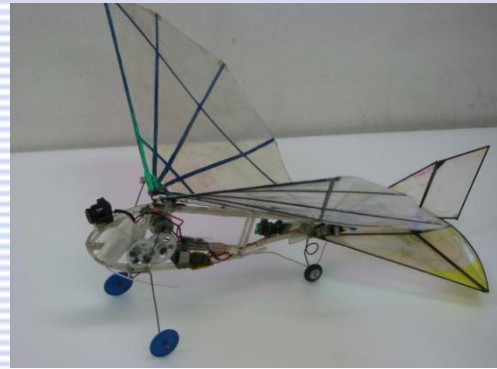


- Different flapping shape due to the elasticity in chord direction

- The deformation of wings of ornithopter and cicada



36cm Flapping MAV



- Landing gear
- Camera attached

Component Part	Mass	Product	Specification
Motor	6.09 g	B2C Motor	Input Voltage (V) 5
Battery	10.0 g	210mA	Output Voltage (V) 8.4
Speed Controller	1.22 g	Falcon HF ESC	
R/C Receiver	2.04 g	GWS Receiver	
Fuselage and Gear Box	6.44 g		Glass plate
Wing Structure	3.27 g		Carbon rod
Camera & transmitter	+6.05 g		
Total Mass	44.60 g(+6.05g)		

36cm Flapping MAV

• Take off



• Landing



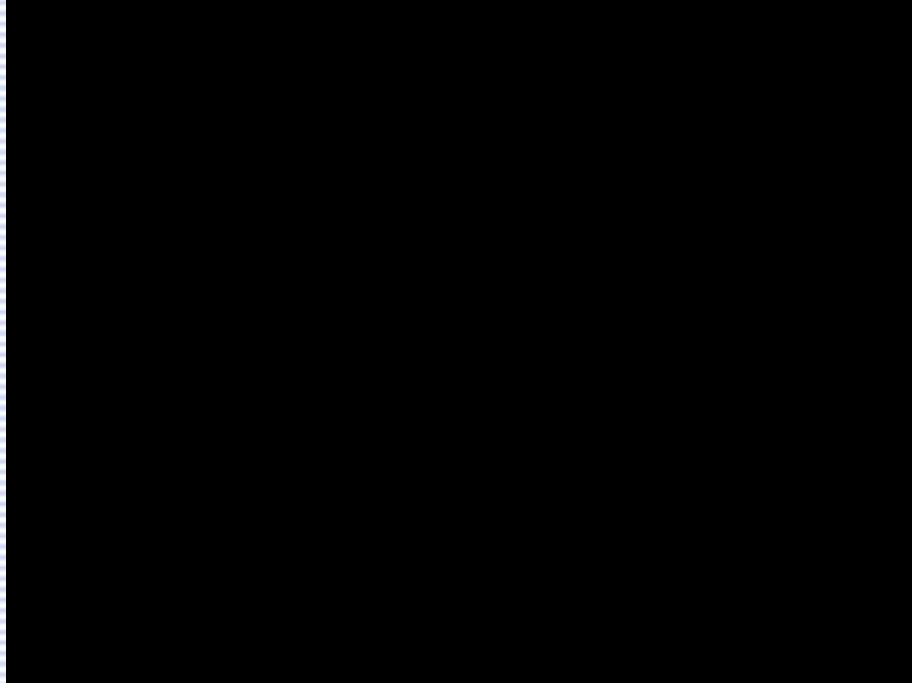
Wing Span	36 cm
Wing Area	432 cm ²
Weight	50 g
Wing loading	0.115g/cm ²
Fuselage	23 cm

Gear Ratio	28:1 reduction
Frequency	20 Hz
Up Stroke °	35°
Down Stroke °	0°
Flight Duration	15 min

3rd US-European Competition and Workshop on MAV Systems

36cm Flapping MAV

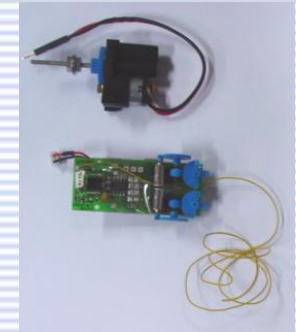
- Flapping and Gliding



- Vision data from camera



28cm Flapping MAV



Component Part	Mass	Product	Specification
Motor	6.09 g	B2C Motor	Input Voltage (V) 5
Battery	7.94 g	145mA battery	Output Voltage (V) 8.4
Speed Controller	1.22 g	Falcon HF ESC	
R/C Receiver	2.04 g	GWS Receiver	
Fuselage and Gear Box	6.44 g		Glass plate
Wing Structure	3.27 g		Carbon road
Total Mass	30.60 g(+3.05g)		

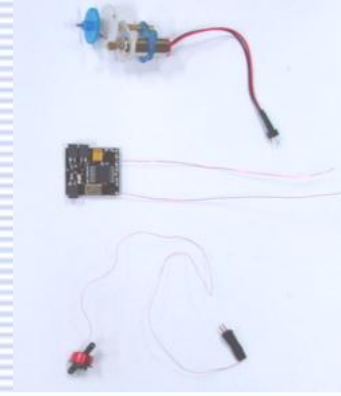
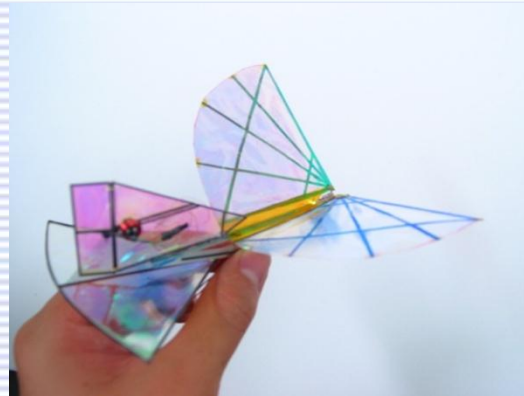
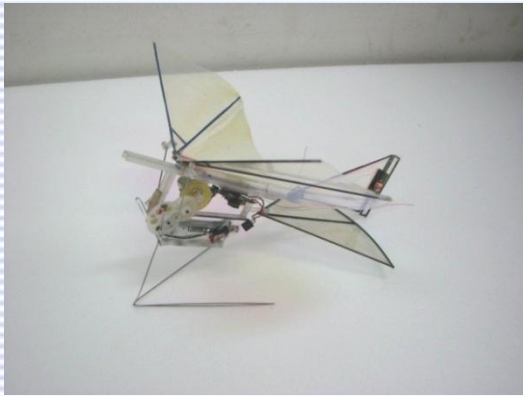
28cm Flapping MAV



Wing Span	28 cm
Wing Area	280 cm ²
Weight	30.6 g
Wing loading	0.109g/cm ²
Fuselage	23 cm
Gear Ratio	19:1 reduction
Frequency	24 Hz
Up Stroke °	30°
Down Stroke °	5 °
Flight Duration	8 min



15cm Flapping MAV



Component Part	Mass	Product	Specification
Motor	1.6 g	Pager motor	Input Voltage (V) 1~3
Battery	1.3 g	60mA battery	Output Voltage (V) 3.7
Speed Controller R/C Receiver	0.8 g		
Fuselage and Gear Box	0.8 g		Glass plate
Wing Structure	6.44 g		Carbon road
Total Mass	8.7 g		

15cm Flapping MAV

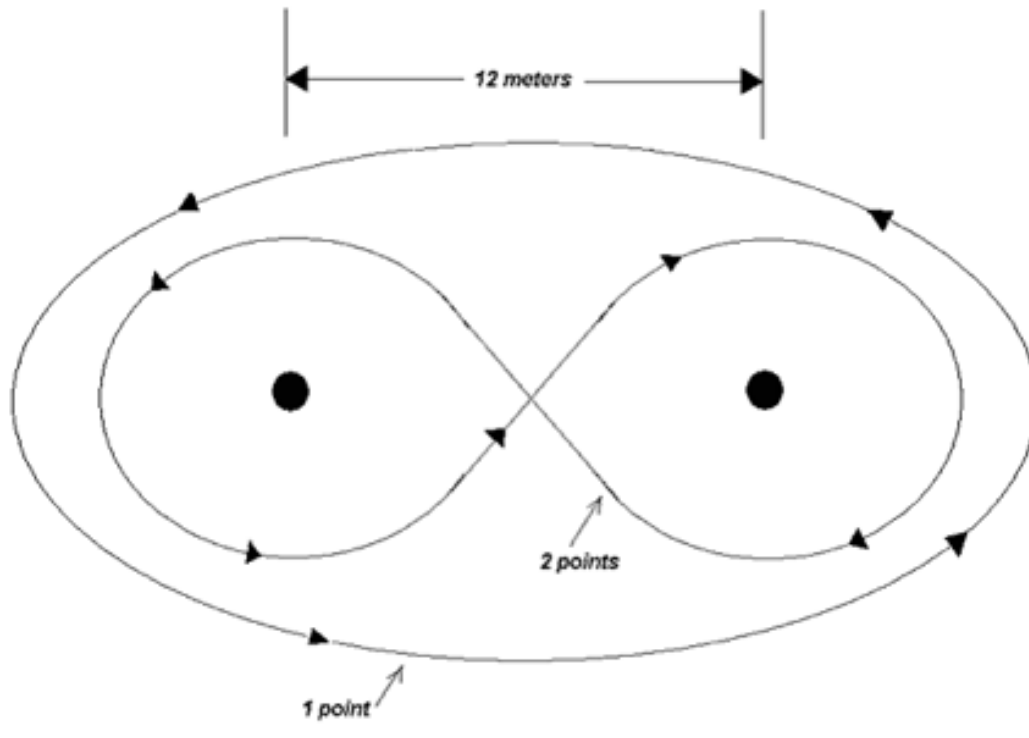


Wing Span	15 cm
Wing Area	85 cm ²
Weight	8.7 g
Wing loading	0.102 g/cm ²
Fuselage	15 cm
Gear Ratio	16:1 reduction
Frequency	30 Hz
Up Stroke °	40°
Down Stroke °	5 °
Flight Duration	1 min

Thank you ...

Ornithopter mission


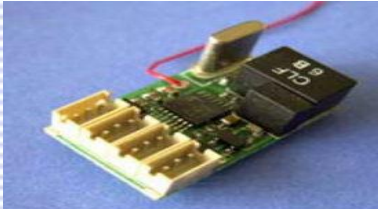

$$\text{Score} = \frac{\text{\#POINTS}}{\text{Dimension}^3}$$



Ranked 4th Place at
9th Int. MAV Competition
2005. 6. Seoul Korea

Ranked 2nd Place at
10th Int. MAV Competition
2006. 5. BYU Utah USA

Component Specification

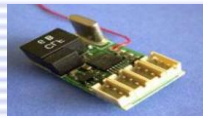
<p>Speed Controller</p>		<p>Falcon HF ESC for 2 Li-poly cells The Falcon High Frequency 100kHz 2 cell ESC is designed to work with 2 Li-poly cells. The ESC incorporates a 5v BEC to power the radio. Data: 1.45g complete with all onnectors and wire. Dimensions: 11mmx15mmx3mm BEC: 5v easily handles 3-4 servos.</p>
<p>Receiver</p>		<p>Gws Rx with JST plugs GWS Rx with JST 4.8 - 6 V Dimensions: 15 x 25 x 10mm Range approx. 150m 4.3g with micro crystal 3.8g without housing</p>
<p>Actuators</p>		<p>Falcon 1.7g Servo Falcon Coreless digital 1.7g servo with JST connectors, Torque 25+grams Operating voltage 3.3 - 5v Length26mm Width.....13mm Height.....14mm For models up to approx150gms</p>

Development Background

- **Conceptual Design**

- **Component Mass**

Component Part	Mass
Motor	6.09 g
Battery	7.94 g
Speed Controller	1.22 g
R/C Receiver	2.04 g
Fuselage and Gear Box	6.44 g
Wing Structure	3.27 g
Total Mass	30.60 g



$$W_{\text{Length}} = 0.74W + 11.2$$



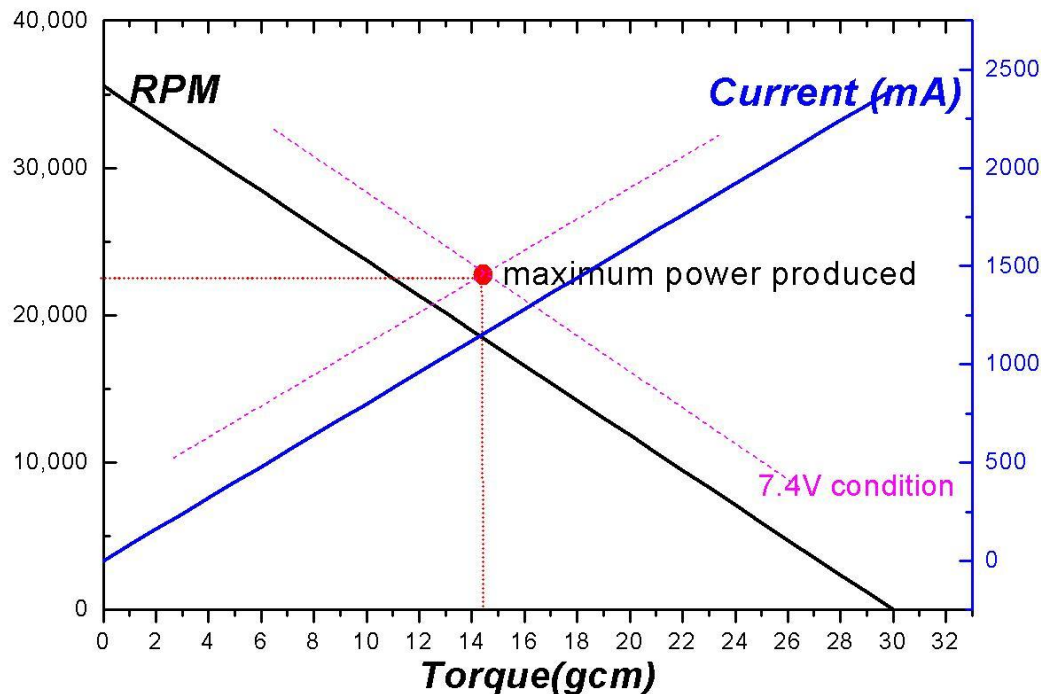
- Maximum assuming weight : 35g
 - Require Wingspan Length = 35cm

- **Design Requirement**

- Wing Span : 35cm
- Weight : max 35g
- Flight endurance : 15 min.
- Remote control range : max 100m
- Materials : composite materials
- Propulsion : electric motor
- Flight control : rudder, elevator

- **Power System**

- Torque value related to RPM & Amp
B2C Motor(4.5V) Performance



- Torque loaded on the wing : min 350 g·cm²
- Maximum torque produced : 15 gcm
- Gear reduction ratio : 23:1

- Selection of Motor :
 - B2C Motor



Norminal Voltage (V)	4.5
Weight (g)	5.6
RPM (No load)	25500
Stall Torque (g·cm)	130

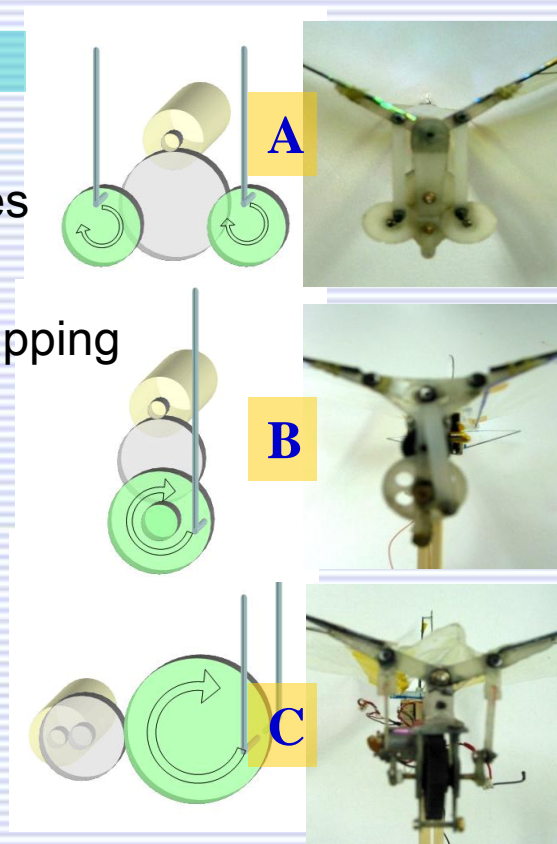
Development Background

- **Gearbox System Design**

- Type of Gear box

Disadvantage

- Heavier than other types
- Non symmetric wing flapping motion
- Structural weakness
- generates higher body vibration relatively



Advantage

- appropriate to transfer large force
- Lighter than others
- Easy to repair
- Strong structure

Type C was compatible in both weight and performance

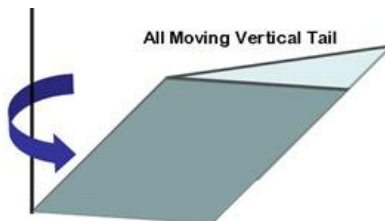
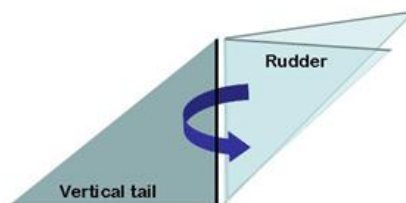
Development Background

- Tail System Design
- 2 types of vertical and horizontal stabilizer

Disadvantage

delay before turning

Less stability after turning

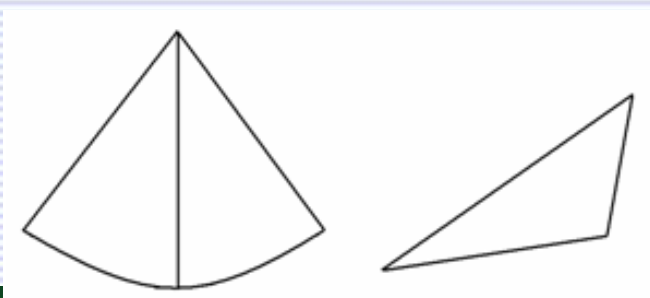


Advantage

very stable in straight and level flight

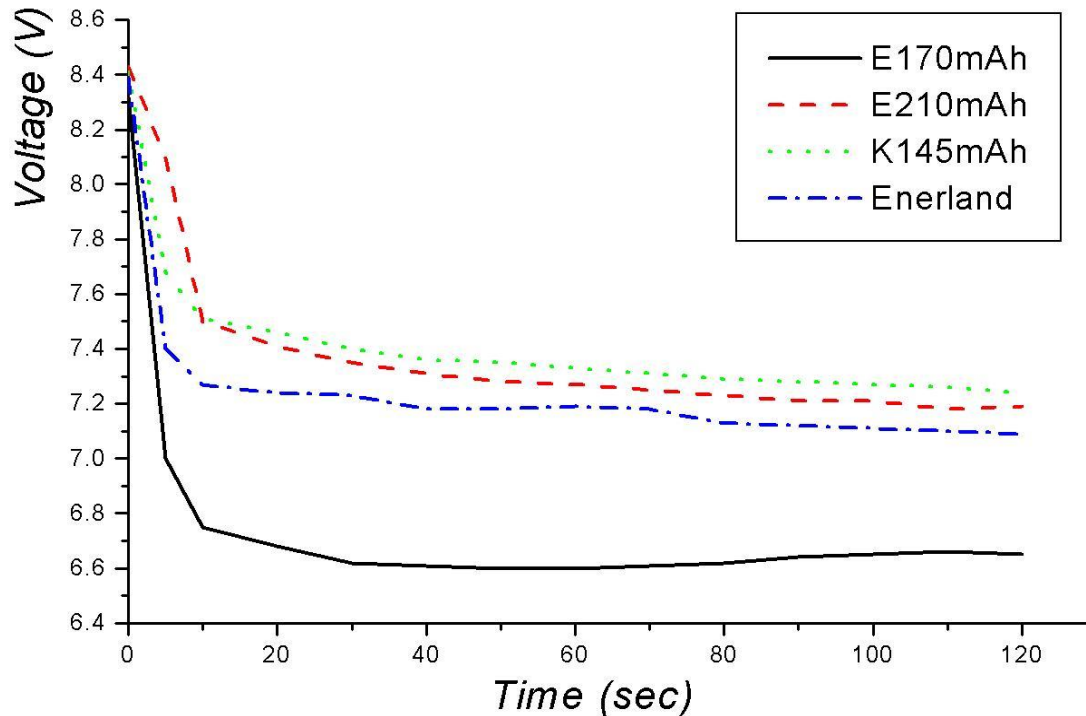
rapid direction change

- The designed vertical and horizontal stabilizer of ornithopter



Development Background

- **Battery Configuration**
- Battery discharge performance
 - Battery type : Li-polymer battery (2-cell)
 - Measured with “Micro-Meter Model 100” device



Battery Requirements

- Supply 1Amp for more than 5 min
- Voltage drop rate should be small